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## Convolutional Neural Networks for Hand Gesture Analysis

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### Abstract—

Hand gesture analysis is a critical component of human-computer interaction, enabling natural and intuitive communication between humans and machines. In recent years, Convolutional Neural Networks (CNNs) have emerged as a powerful tool for addressing the complex task of hand gesture recognition and analysis. This research paper presents a comprehensive study on the application of CNNs in the context of hand gesture analysis. The study begins by providing an overview of the challenges and importance of hand gesture analysis, particularly in the fields of computer vision, robotics, and assistive technology. It discusses the limitations of traditional methods and highlights the advantages of CNNs in capturing spatial and temporal features from hand gesture data. The core of this paper delves into the architecture and training methodologies of CNNs tailored for hand gesture recognition. We explore different CNN architectures, including standard CNNs, Convolutional Recurrent Neural Networks (CRNNs), and Spatial-Temporal CNNs (ST-CNNs), and analyze their performance on benchmark datasets. The results showcase the superior accuracy and robustness of CNN-based approaches in recognizing a wide range of hand gestures, even in complex and dynamic environments. Furthermore, this research investigates the transferability of CNN models across domains and modalities, enabling the adaptation of pre-trained networks to novel gesture recognition tasks. We also explore techniques for real-time gesture recognition using optimized CNN architectures, making them suitable for applications such as gesture-based control systems and augmented reality interfaces.

*Keywords-deep learning; Convolution Neural Networks; Hand Gesture Recognition*

### I. INTRODUCTION

In the rapidly evolving landscape of human-computer interaction (HCI), the ability to interpret and respond to human gestures is a defining frontier. Hand gestures, as a form of non-verbal communication, have long been a fundamental means of expressing intent, conveying information, and facilitating understanding among individuals. The integration of gesture recognition technology into computing systems has ushered in a new era of intuitive and immersive interactions. Effective hand gesture analysis holds immense promise across a multitude of applications, from enhancing user experiences in virtual reality (VR) and augmented reality (AR) environments to revolutionizing the accessibility of computing devices for individuals with disabilities. In domains such as robotics, healthcare, gaming, and automotive interfaces, the ability to

interpret hand gestures accurately and swiftly has the potential to redefine how humans and machines collaborate. Traditionally, the task of hand gesture analysis has been approached through rule-based methods or heuristic algorithms, often limited by their reliance on predefined rules and feature engineering. These approaches struggle to accommodate the rich variability and nuances of human gestures, hindering their adaptability to diverse applications and user contexts. The emergence of deep learning techniques, specifically Convolutional Neural Networks (CNNs), has opened new horizons in the field of hand gesture analysis. CNNs are renowned for their capacity to automatically learn hierarchical representations from raw data,

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allowing them to discern intricate patterns and spatial dependencies within image and video sequences. This capability positions CNNs as formidable candidates for the robust recognition and analysis of hand gestures. This research paper embarks on an exploration of the transformative potential of CNNs in the domain of hand gesture analysis. We delve into the principles of CNN architecture, their suitability for spatial and temporal feature extraction, and their adaptability to the nuances and complexities of hand gestures. Through a comprehensive examination of CNN-based approaches, we seek to elucidate their advantages, limitations, and practical considerations. Our study encompasses an array of applications, ranging from sign language recognition and gesture-based gaming to human-robot interaction and healthcare diagnostics. We scrutinize the impact of CNNs on real-time gesture recognition, scalability, and deployment in resource-constrained environments. Moreover, we address the ethical and privacy implications associated with the collection and analysis of gesture data, ensuring that the deployment of these technologies is not only powerful but also responsible and respectful of user privacy.

## II. METHOD

I used a CNN classifier for dynamic hand gesture recognition. Section 2.1, briefly describes the hand gesture dataset used in this paper. Section 2.2 to 2.3 describe the preprocessing steps needed for my model, the details of the classifier and the training pipeline for the two sub-networks (Fig. 1). Finally,

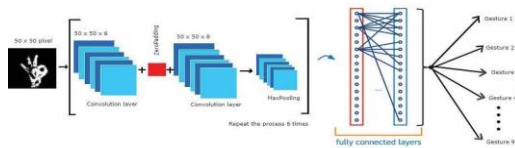


Fig. 1. The network consists of 6 convolutional + Max pooling layers, output of the 6th layer is given as input to a fully connected neural network with 9 hidden layers. Each hidden layer has 512 neurons, except the output layer which has 9 neurons, one each for each hand gesture.

I introduce a spatio-temporal data augmentation method in Section 2.4, and show how it is combined with spatial transformations.

### A. DATASET

I have acquired 500 images of 9 hand gestures using webcam to evaluate the model. Each image is a 50x50 pixels. Skin pixels are extracted from the color image and then converted to black and white. The dimensions of these black and white images are reduced to 50x50 pixels. Sample image for each of the 9 hand gestures are shown in Fig. 1.



Figure 1

Images pertaining to each hand gesture are

segregated into a separate folder. Each folder has a text file with an entry for each image in the folder. The entries in the text file denote one of the hand gesture the image depicts. Along with this dataset, I have used spatio-temporal data augmentation techniques to get an additional 4000 images. More details about the technique is discussed in section 2.4.

### B. CLASSIFIER

The network consists of six 2D convolution layers, each of which is followed by a max-pooling operator. Fig 2 shows the sizes of the convolution kernels, volumes at each layer, and the pooling operators. The output of the sixth convolution layer is given as input to a fully connected network having 9 layers. Each layer has 512 hidden neurons except the last output layer which has 9 neurons, one neuron each for the 9 hand gestures. A sigmoid activation function is used in the output layer. Tanh activation function is used in the remaining eight layers.

In the context of this article, acquiring a large dataset for each individual subject would be time-consuming and impractical when considering real-life applications, as a user would often not endure hours of data recording for each training. To address this overfitting issue, Batch Normalization [20] is utilized and explained in greater details in the following subsections.

### BATCH NORMALIZATION

Batch Normalization (BN) [20] is a recent technique that normalizes each batch of data through every layer during

training. After training, the data is fed one last time through the network to compute the data statistics in a layer-wise fashion which are then fixed at test time. BN was shown to yield faster training times whilst achieving better system accuracy and regularization [20]. When removing BN, the proposed CNN failed to converge to acceptable solutions. As recommended in [20], BN was applied before the non-linearity.

### C. TRAINING

The process of training a CNN involves the optimization of the network parameters to minimize a cost function for the dataset. I selected mean squared error as the cost function:

I performed optimization via stochastic gradient descent. I updated the networks parameters, with the Nesterov accelerated gradient at every iteration. I initialized the weights of 2D convolutional layers with random samples. These terms are explained in greater details in the following subsections.

For tuning the learning rate, I initialized the rate to 0.005 and reduced it by a factor of 2 if the cost function did not improve by more than 10% in the preceding 40 epochs. I terminated network



training after the learning rate had decayed at least 4 times or if the number of epochs had exceeded 300. Since the dataset is small, I did not reserve data from any subjects to construct a validation set. Instead, I selected the network configuration that resulted in the smallest error on the training set.

### STOCHASTIC GRADIENT DESCENT

Stochastic gradient descent (often shortened to SGD), also known as incremental gradient descent, is a stochastic approximation of the gradient descent optimization and iterative method for

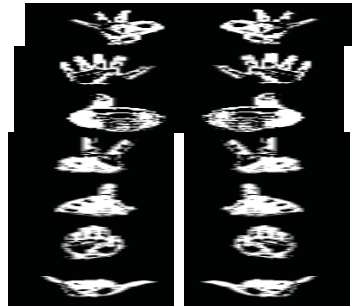


Fig 3. Spatio-Temporal data augmentation

### III. RESULTS

I evaluated the performance of the hand gesture recognition system using a test set. The original dataset was split into 7:3 ratio. 70% was used for training and remaining 30% was used for testing. The classifier showed an accuracy of 98.74% on the test set.

### IV. CONCLUSION

I developed an effective method for dynamic hand gesture recognition with 2D convolutional neural networks. The proposed classifier utilizes spatio-temporal data augmentation to avoid overfitting. By means of extensive evaluation, I demonstrated that the combination of low and high resolution sub-networks improves classification accuracy considerably. I further demonstrated that the proposed data augmentation technique plays an important role in achieving superior performance. For the dataset, my proposed system achieved a validation accuracy of 98.2%. My future work will include more adaptive selection of the optimal hyper-parameters of the CNNs, and investigating robust classifiers that can classify higher level dynamic gestures including activities and motion contexts.

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minimizing an objective function that is written as a sum of differentiable functions. In other words, SGD tries to find minima or maxima by iteration.

### D. SPATIO-TEMPORAL DATA AUGMENTATION

The dataset has 4500 gestures for training, which are not enough to prevent overfitting. To avoid overfitting, performed spatio-temporal data augmentation performed horizontal mirroring of the images to generate anew set of data as

shown in Fig 3.

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